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In general, barometric pressure is related to wind speed: Lower pressure is associated with a stronger storm, and a stronger storm is associated with higher winds.

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Example: We want to predict the highest sustained wind speed in a tropical storm at some point over the ocean, and we know the barometric pressure.

In general, barometric pressure is related to wind speed: Lower pressure is associated with a stronger storm, and a stronger storm is associated with higher winds.

A model is desirable because barometric pressure is more stable than wind speed and can be measured more easily.

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- Y represents a quantity we want to predict
- $\checkmark$  X represents a related quantity we can measure

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where  $\beta$  is some coefficient we can think of as a parameter that can be estimated from a sample.

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There is a philosophical problem with this model though: it is **deterministic**.

The model says we know Y **exactly** if we know the value of X.

#### **Deterministic Model**



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Now we are simply stating that the expected value or population mean  $\mu_Y$  of *Y* given *X* is  $\beta X$ 

This avoids the requirement that every *Y* value exactly match  $\beta X$ .

For an individual observation  $Y_i$  with associated value  $X_i$ , we solve the problem of introducing randomness differently. We represent an individual observation as:

$$Y_i = \beta X_i + e_i$$

where:

- $\beta$  is a parameter (a constant to a frequentist, a random variable to a Bayesian)
- $X_i$  is a **known** constant
- $e_i$  is a random variable with expected value  $E(e_i) = \mu_e = 0$  and standard deviation  $\sigma_e$

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Now  $Y_i$  is a random variable. The randomness of  $Y_i$  arises from  $e_i$  (and, in the Bayesian approach, also from  $\beta$ ).

## **Linear Models - Frequentist**

From the properties of expected values, recall that

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In the classical or frequentist approach,  $\beta$  and  $X_i$  are constants, and the expected value of a constant is just its value, so

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We are assuming that  $E(e_i) = 0$  for each  $e_i$ , so

$$E(Y_i) = \beta X_i + 0 = \beta X_i$$

which agrees with the earlier result.

# **Linear Models - Bayesian**

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In the Bayesian approach,  $\beta$  is treated as a random variable and we have to assume a particular probability distribution for it. This is called the **prior** distribution of  $\beta$ . In the expression below,  $E(\beta)$  represents the expected value of  $\beta$ with respect to this distribution. Once again the  $X_i$  are constants and are equal to their expected values, so this time we can write

$$E(Y_i) = E(\beta) \cdot X_i + E(e_i)$$

# **Linear Models - Bayesian**

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We are assuming that  $E(e_i) = 0$  for each  $e_i$ , so

$$E(Y_i) = E(\beta)X_i + 0 = E(\beta)X_i$$

So to a frequentist,

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To a frequentist,  $\beta$  is a constant, while a Bayesian considers it to be a random variable having the prior distribution.

The prior distribution is subjective, and can be thought of as a mathematical model of the researcher's uncertainty about the value of  $\beta$ .

Which point of view is better, frequentist or Bayesian?

Which point of view is better, frequentist or Bayesian? This question has been (and continues to be) a source of controversy and debate within the statistics community. Both have advantages and disadvantages.

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This question has been (and continues to be) a source of controversy and debate within the statistics community. Both have advantages and disadvantages.

People in applied statistics usually try to be pragmatic and choose an approach that makes sense in the context of the data they have to work with and the question they are trying to answer.

The good news is that as the sample size becomes larger, the most common frequentist techniques and their Bayesian counterparts converge to the same limit.

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This limit is called the **maximum likelihood** estimate of  $\beta$ , meaning an estimate that makes the probability of observing the sample you actually got as large as possible.

We saw a similar situation when we considered the normal and t distributions for constructing confidence intervals.

If you had a large enough sample, you got essentially the same answer regardless of which one you used.

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How much information to incorporate in the prior, and how to go about it, remains a difficult question and is an active area of research.

There is some agreement that choosing a prior distribution that imposes no restrictions on the value of  $\beta$  is acceptable when there is outside information to be incorporated in the analysis, and this is the approach we will take.

We will use R to generate a model of this type.

First generate 1000 values for the  $X_i$ : Pick 1000 values between zero and 100 with the command:

*x*<-100\**runif*(1000)
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Now generate 1,000  $e_i$  values as normal random variables with mean zero and standard deviation 5:

e<-rnorm(1000,0,5)

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Now generate 1,000  $e_i$  values as normal random variables with mean zero and standard deviation 5:

*e*<-*rnorm*(1000,0,5) Finally generate the  $Y_i$  values as  $Y_i = \beta X_i + e_i$ 

y<-beta\*x+e

#### **Data Plot: Beta=2 Sigma=5**

plot(x,y)



#### **Data Plot: Beta=2 Sigma=0**

Compare with the deterministic model  $Y = \beta X$ :



Now we examine the effect of larger values of  $\sigma_e$ :

Generate 1,000  $e_i$  values as normal random variables with mean zero and standard deviation 10:

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y<-beta\*x+e

Now examine the plot of x and y.

## Beta=2 Sigma=10



Repeat the process with  $\sigma_e = 70$ .

Generate 1,000  $e_i$  values as normal random variables with mean zero and standard deviation 70:

e<-rnorm(1000,0,70)

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Now examine the plot of x and y.

#### Beta=2 Sigma=70



Next repeat the process with  $\sigma_e = 150$ .

Generate 1,000  $e_i$  values as normal random variables with mean zero and standard deviation 150:

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*y<-beta\*x+e* 

Now examine the plot of x and y.

## Beta=2 Sigma=150

The trend is less obvious as the "noise" level increases:



Finally repeat the process with  $\sigma_e = 1000$ .

Generate 1,000  $e_i$  values as normal random variables with mean zero and standard deviation 1000:

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Generate 1,000  $e_i$  values as normal random variables with mean zero and standard deviation 1000:

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*y<-beta\*x+e* 

Now examine the plot of x and y.

## Beta=2 Sigma=1000

By now the trend is barely discernable:



We just examined a model of the form

$$Y_i = \beta X_i + e_i$$

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Notice that both  $Y_i$  and  $X_i$  are continuous, that is, they can assume any value.

Now we examine a variation that allows us to use a linear model to compare the means of more than two groups.

We have developed techniques for comparing the means of two populations, but what we consider next will apply to more general types of comparisons.

Suppose we want to compare the means of three groups, and we have samples from each group.

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This time the linear model looks like this:

$$Y_i = \mu + \beta_1 X_{1i} + \beta_2 X_{2i} + \beta_3 X_{3i} + e_i$$

Where:

- $X_{1i}$  equals 1 if  $Y_i$  is in group 1, and zero otherwise
- $X_{2i}$  equals 1 if  $Y_i$  is in group 2, and zero otherwise
- $X_{3i}$  equals 1 if  $Y_i$  is in group 3, and zero otherwise
- $\mu$ ,  $\beta_1$ ,  $\beta_2$ , and  $\beta_3$  are parameters (constants)

As before, the  $X_{ij}$ s and  $\beta$ s are constants, and the  $e_i$ s are random variables with mean  $\mu_e = 0$  and standard deviation  $\sigma_e$ . Then because the  $X_{ij}$  values corresponding to the groups  $Y_i$  does not belong to are zero, we can write:

• 
$$Y_i = \mu + \beta_1 X_{1i} + e_i$$
 if  $Y_i$  is in group 1

• 
$$Y_i = \mu + \beta_2 X_{2i} + e_i$$
 if  $Y_i$  is in group 2

• 
$$Y_i = \mu + \beta_3 X_{3i} + e_i$$
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The expected values for the  $Y_i$ s are:

• 
$$E(Y_i) = \mu + \beta_1 X_{1i} = \mu + \beta_1$$
 if  $Y_i$  is in group 1

• 
$$E(Y_i) = \mu + \beta_2 X_{2i} = \mu + \beta_2$$
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• 
$$E(Y_i) = \mu + \beta_3 X_{3i} = \mu + \beta_3$$
 if  $Y_i$  is in group 3

For example, suppose there are 9 data values in the sample, 3 from each group.

Then the *Y* and *X* values are:

Y	$X_{1i}$	$X_{2i}$	$X_{3i}$
$Y_1$	1	0	0
$Y_2$	1	0	0
$Y_3$	1	0	0
$Y_4$	0	1	0
$Y_5$	0	1	0
$Y_6$	0	1	0
$Y_7$	0	0	1
$Y_8$	0	0	1
$Y_9$	0	0	1

Now we will construct artificial data with 3,000 observations, 1,000 in each of three groups with the following characteristics:

- $\mu = 1$ •  $\beta_1 = 1$
- $\beta_2 = 3$
- $\beta_3 = 5$

The expected values for the three groups are:

• 
$$E(Y_i) = \mu + \beta_1 = 1 + 1 = 2$$
 if  $Y_i$  is in group 1

- $E(Y_i) = \mu + \beta_2 = 1 + 3 = 4$  if  $Y_i$  is in group 2
- $E(Y_i) = \mu + \beta_3 = 1 + 5 = 6$  if  $Y_i$  is in group 3

As before we will use R to generate the model.

First generate 1000 values for each of three groups, with values 1, 3, and 5:

x<-c(rep(1,1000),rep(3,1000),rep(5,1000))

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x<-c(rep(1,1000),rep(3,1000),rep(5,1000))
Next assign a value to \mu. We'll use 1:
```

*mu<-1* 

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First generate 1000 values for each of three groups, with values 1, 3, and 5:

x<-c(rep(1,1000),rep(3,1000),rep(5,1000)) Next assign a value to  $\mu$ . We'll use 1:

*mu<-1* 

Now generate 3,000  $e_i$  values as normal random variables with mean zero and standard deviation 1:

e<-rnorm(3000,0,1)

As before we will use R to generate the model.

First generate 1000 values for each of three groups, with values 1, 3, and 5:

```
x<-c(rep(1,1000),rep(3,1000),rep(5,1000))
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Now generate 3,000  $e_i$  values as normal random variables with mean zero and standard deviation 1:

```
e<-rnorm(3000,0,1)
```

Now generate the  $Y_i$  values:

y<-mu+x+e
## **Generating the Data**

Now generate the group labels:

group <- gl(3,1000,3000, labels=c("Group1","Group2","Group3"))

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Now generate the group labels:

group <- gl(3,1000,3000, labels=c("Group1","Group2","Group3"))
Finally, produce a box plot of the data:

 $\mathsf{boxplot}(y \sim group)$ 

## mu=1 beta1=1 beta2=2 beta3=3

The following is a boxplot of the data:

