
Linear Transformations

Gene Quinn

Functions

First a review of the concept of a function is in order.

A formal definition of a function usually involves three entities:

- A set X called the *domain*
- A set Y which is sometimes called the *codomain*
- A **rule of assignment** that assigns a *unique* element of the codomain Y to every element of the domain X .

Functions

The bulk of one's early experience is usually with functions whose domain X and codomain Y are the real numbers, and the rule of assignment is a formula, say

$$y = x^2 + 2$$

Functions

In the study of linear algebra, we will be dealing with functions whose domain and codomain are sets of *vectors*.

We identify a vector \vec{x} having n components with an *ordered n -tuple* of scalars (real numbers, in this course):

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

corresponds to the ordered n -tuple $(x_1, x_2, \dots, x_n) \in \mathbb{R}^n$.

Linear Transformations

We will consider the class of functions T for which:

- the domain is the set of m -tuples of real numbers \mathbb{R}^m
- the codomain is the set of n -tuples of real numbers, \mathbb{R}^n

In mathematics, this situation is denoted by:

$$T : \mathbb{R}^m \rightarrow \mathbb{R}^n$$

Linear Transformations

Definition: A **linear transformation** is a function T that maps \mathbb{R}^m into \mathbb{R}^n ,

$$T : \mathbb{R}^m \rightarrow \mathbb{R}^n$$

in such a way that there exists an $n \times m$ matrix A with the property that

$$T(\vec{x}) = A\vec{x}$$

for every $\vec{x} \in \mathbb{R}^m$.

Linear Transformations

The following properties characterize linear transformations:

A transformation $T : \mathbb{R}^m \rightarrow \mathbb{R}^n$ is **linear** if and only if

$$T(\vec{u} + \vec{v}) = T(\vec{u}) + T(\vec{v}) \quad \text{for all } \vec{u}, \vec{v} \in \mathbb{R}^m$$

$$T(k\vec{v}) = kT(\vec{v}) \quad \text{for all } \vec{v} \in \mathbb{R}^m \text{ and all scalars } k$$

The Matrix of a Linear Transformation

We have seen that every linear transformation $T : \mathbb{R}^m \rightarrow \mathbb{R}^n$ is associated with an $n \times m$ matrix A with the property that

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As it turns out there is a relationship between the columns of the matrix A and the image under T of vectors of the form

$$\vec{e}_i = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix}$$

The Matrix of a Linear Transformation

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The vector \vec{e}_i has every component zero except for the i^{th} , which is 1.

The Matrix of a Linear Transformation

The $n \times n$ matrix A associated with the linear transformation $T : \mathbb{R}^m \rightarrow \mathbb{R}^n$ is:

$$A = [T(\vec{e}_1) \quad T(\vec{e}_2) \quad \cdots \quad T(\vec{e}_m)]$$

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In other words,

- the first column of A is the vector in \mathbb{R}^n that T maps \vec{e}_1 into
- the second column of A is the vector in \mathbb{R}^n that T maps \vec{e}_2 into
- the third column of A is the vector in \mathbb{R}^n that T maps \vec{e}_3 into
- the k^{th} column of A is the vector in \mathbb{R}^n that T maps \vec{e}_k into

The Matrix of a Linear Transformation

The vectors

$$\vec{e}_1, \vec{e}_2, \dots, \vec{e}_m \in \mathbb{R}^m$$

are sometimes called the **standard vectors** in \mathbb{R}^m .

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In \mathbb{R}^3 , the standard vectors \vec{e}_1 , \vec{e}_2 , and \vec{e}_3 are usually denoted by $\vec{i}, \vec{j}, \vec{k}$.