### **Sullivan Section 3.2**

Gene Quinn

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Central tendency measures tell only part of the story.

Usually, we also need to know how data values "spread out" or disperse around an average. Measures of this characteristic of data are known as **measures of dispersion** 

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Measures of dispersion give an indication of how precise or how reliable an average is.

Stating an average by itself is much less useful than stating an average together with some measure of its reliability.

# **The Range**

The simplest measure of dispersion is the range.

**Definition:** The **range R** of a variable is the difference between the largest data value and the smallest:

Range = R = Largest data value - Smallest data value

# **The Range**

#### Example:

If we measured the weights of a group of people and obtained the following data,

146, 185, 157, 225, 120, 190, 216

The Range R would be:

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= 225 - 120 = 105

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Since we have two kinds of means, the population mean  $\mu$  and the sample mean  $\overline{x}$ , we also have two kinds of deviations about the mean.

For the deviation of the  $i^{th}$  data value about the *population* mean, we compute

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$$x_i - \overline{x}$$

Since we are interested in the **average** deviation about  $\mu$  for a population,

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in either case, the average deviation about the appropriate mean would seem to be the natural choice.

Unfortunately, there is a problem with this approach.

In both cases, the average deviation about the mean is **always** zero, because of the way that the means are calculated:

Deviations can be positive or negative, and the positive and negative deviations cancel each other out.

One way to prevent this cancellation is to **square** the deviations before we add them up.

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This technique used in a measure of dispersion called the **variance**.

As with means, we will need to define two variances: a *population* variance and a *sample* variance.

## **The Population Variance**

#### **Definition:**

The **population variance** of a variable, denoted by the symbol  $\sigma^2$ , is the sum of the squared deviations from the population mean, taken over the entire population:

$$\sigma^{2} = \frac{(x_{1} - \mu)^{2} + (x_{2} - \mu)^{2} + \dots + (x_{N} - \mu)^{2}}{N}$$

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The **sample variance** of a variable, denoted by the symbol  $s^2$ , is the sum of the squared deviations from the sample mean, taken over the sample:

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In this formula,  $\overline{x}$  is the sample mean, and  $x_1, x_2, \ldots, x_n$  are the *n* observations in the population.

Note that the divisor in the sample variance is n-1 and not n.

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It can be shown mathematically that if we use n - 1, the sample variance will be free of **bias** as an estimator of the population variance.

We say that an estimator has no bias, or is unbiased, if it has no tendency to either consistently overestimate or consistently underestimate the population variance.

If we used *n* as the divisor in computing  $s^2$ , we would obtain a **biased** estimate of the population variance  $\sigma^2$  ( $s^2$  would consistently underestimate  $\sigma^2$ ). The value n - 1 in the sample variance is referred to as the number of **degrees of freedom** 

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This term originates from the fact that, if we have n numbers and their mean, one of the numbers is superfluous.

That is, if I know the sample mean and n-1 of the *n* sample values, I can always figure out what the  $n^{th}$  sample value is.

Another way to say this is that, once I have n - 1 data values and the mean, I have no freedom in the choice of the  $n^{th}$  data value.

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The **population standard deviation**, denoted by  $\sigma$ , is the square root of the population variance:

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The **sample standard deviation**, denoted by *s*, is the square root of the sample variance:

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The standard deviation is a measure of dispersion in the sense that, the larger the standard deviation, the more the data values are dispersed around the mean.

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Approximately 95 percent of the data will lie within 2 standard deviations of the population mean (that is, between  $\mu - 2\sigma$  and  $\mu + 2\sigma$ ).

Approximately 99.7 percent of the data will lie within 3 standard deviations of the population mean (that is, between  $\mu - 3\sigma$  and  $\mu + 3\sigma$ ).

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We say  $P_{90}$  is the  $90^{th}$  percentile of a measure for a population if 90% of the individuals in the population have a value of  $P_{90}$  or less.

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The median M is the same as the  $50^{th}$  percentile,  $P_{50}$ .

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The  $75^{th}$  percentile  $P_{75}$  is called the **third quartile**  $Q_3$ .

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